# Graphon mean-field BSDEs with jumps and associated dynamic risk measures

Agnès Sulem

INRIA Paris Equipe-Projet MATHRISK



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joint work with Hamed Amini (University of Florida) & Zhongyuan Cao (NYU Shangaï)

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- Motivated by various applications, mean-field systems and mean-field games on large networks have been explored for different random graph models, e.g. Erdös-Rényi graph (Delarue 2017) or heterogeneous random graphs (Oliveira and Reis 2019).
- Recently, the use of graphons has emerged in order to analyze heterogeneous interactions in mean-field systems and game theory, (see Caines, Carmona, Bayraktar, Lacker, Laurière ...)

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• Our goal here is to study Graphon Mean Field BSDEs with jumps

# Outline

# BSDE with jumps with general mean-field operators The driver of the BSDE contains a mean-field term which can accomodate several types of interactions; in particular higher order interactions

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Extend the study by the introduction of graphon interaction in the driver to capture heterogeneous interactions

# Mean-field BSDEs with jumps

Let  $(\Omega, \mathcal{F}, P)$  be a probability space; Let W be a Brownian motion;  $\tilde{N}(dt, de)$  the compensated process of a Poisson r.m. N(dt, de) with compensator v(de)dt s.t. v is a  $\sigma$ -finite positive measure on  $\mathbb{R}^*$ . Let  $\mathbf{F} = \{\mathcal{F}_t, t \ge 0\}$  the natural filtration associated with W and N. Let T > 0.

$$-dX_t = f(t, \omega, F(t, X_t), X_t, Z_t, I_t(\cdot))dt - Z_t dW_t - \int_{\mathbb{R}^*} I_t(e) \tilde{N}(dt, de)$$
$$X_T = \xi \in L^2(\mathcal{F}_T)$$

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where *f* is a *Lipschitz driver* and *F* is a Lipschitz mean-field operator  $F : [0, T] \times L^2(\mathcal{F}_T) \to \mathbb{R}, (t, X) \mapsto F(t, X)$  is measurable,  $\forall t \in [0, T], F(t, 0) < +\infty$ , and  $\exists C \ge 0$  s.t.  $\forall (X_1, X_2) \in L^2(\mathcal{F}_T) \times L^2(\mathcal{F}_T), |F(t, X_1) - F(t, X_2)| \le C ||X_1 - X_2||_2.$ 

#### Examples of mean-field operators

- First order interactions : F(t, X) := E[φ(t, X)], where φ is a Lipschitz function s.t. φ(t, X) ∈ L<sup>2</sup>(𝓕<sub>T</sub>).
- Second order mean-field interaction term :

$$F(t,X) = \int_{\mathbb{R}\times\mathbb{R}} \kappa(x,x')\mu_t(dx)\mu_t(dx') = \mathbb{E}\left[\kappa(X,X')\right], \left((X,X')\sim\mu_t\otimes\mu_t\right)$$

where  $\kappa$  is a Lipschitz kernel that captures the intensity of interactions, and X' is an independent copy of the same distribution  $\mu_t$  as X. The operator F may represent the average intensity of interactions of nodes in an inhomogeneous random graph (Bollobas et al 07).

 $\mapsto$  When the kernel  $\kappa$  is constant in its first argument, we recover the expectation operator.

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#### Results

# Results

- Existence and Uniqueness results
- Comparison theorems under appropriate monotony assumptions on *f* and *F*
- Dual representation in the convex case

R. Chen, R. Dumitrescu, A. Minca, and A.S. : Mean-field BSDEs with jumps and dual representation for global dynamic risk measures. *Probability, Uncertainty and Quantitative Risk*, 8(1) :33–52, 2023

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We now turn to the study a class of mean field BSDEs with coupling specified via a graphon, to account for heterogeneity of a continuum of agents.

- Graphons have been developed by Lovász et al., as a natural continuum limit object for large dense graphs.
- A graphon is a symmetric measurable fn G : I<sup>2</sup> → I, with I := [0,1] indexing a continuum of possible positions for nodes in the graph and G(u, v) representing the edge density between nodes placed at u and v.

The so-called cut norm of a graphon is defined by

$$\|G\|_{\Box} := \sup_{A,B\in\mathscr{B}(I)} \left| \int_{A\times B} G(u,v) du dv \right|.$$

We can also view a graphon as an operator from L<sup>∞</sup>(I) to L<sup>1</sup>(I), defined for any φ ∈ L<sup>∞</sup>(I) as :

$$G\phi(u) := \int_{I} G(u, v)\phi(v) dv.$$

#### Spaces of processes

Let  $\mathbb{J} = \mathcal{I}_t, t \ge 0$  be a filtration defined on some probability space

- $L^2(\mathcal{I}_t)$  : set of all  $\mathcal{I}_t$ -measurable and square integrable r.v. for  $t \in [0, T]$ .
- $\mathbb{H}^2(\mathbb{J})$  is the set of all real-valued  $\mathbb{J}$ -predictable processes  $\phi$  such that

$$\|\phi\|_{\mathbb{H}^2} := \left(\mathbb{E}\left[\int_0^T \phi_t^2 dt\right]\right)^{1/2} < \infty.$$

•  $\mathbb{H}^2_{\nu_u}(\mathbb{J})$  (for each  $u \in I$ ) is the set of all  $\mathbb{J}$ -predictable function-valued processes  $\ell$  such that

$$\|\ell\|_{\mathbb{H}^2_{v_u}} := (\mathbb{E}[\int_0^T \|\ell_t\|^2_{v_u} dt])^{1/2} < \infty.$$

- $\mathbb{S}^2(\mathbb{J})$  is the set of all real-valued RCLL  $\mathbb{J}$ -adapted processes  $\phi$  with  $\|\phi\|_{\mathbb{S}^2} := (\mathbb{E}[\sup_{t \in [0,T]} |\phi_t|^2])^{1/2} < \infty.$
- $\mathcal{MS}^2(\mathbb{J})$  is the set of all measurable functions X from I to  $\mathbb{S}^2(\mathbb{J}) : u \mapsto X_u$ , satisfying  $\sup_{u \in I} ||X_u||_{\mathbb{S}^2}^2 = \sup_{u \in I} \mathbb{E}[\sup_{t \in [0,T]} |X_u(t)|_{\mathbb{C}}^2] < \infty$ .

(INRIA, Mathrisk)

# Probability setup

Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a complete probability space. Let I = [0, 1].

- Let  $\{W_u : u \in I\}$  be a family of independent Brownian motions.
- Let {N<sub>u</sub>(dt, de) : u ∈ I} be a family of independent Poisson measures with compensator v<sub>u</sub>(de)dt such that v<sub>u</sub> is a probability measure on E := ℝ<sub>\*</sub>, for each u ∈ I. Let {Ñ<sub>u</sub>(dt, de) : u ∈ I} be their compensator processes.
- Let F = {*F<sub>t</sub>*, t ≥ 0} be the natural filtration associated with {*W<sub>u</sub>* : u ∈ l} and {*N<sub>u</sub>*(*dt*, *de*) : u ∈ l}.
   Let T > 0. Denote by P the predictable σ-algebra on [0, T] × Ω.
- For each  $u \in I$ , let  $\mathbb{F}^u = \{\mathcal{F}_t^u, t \ge 0\}$  be the augmented filtration generated by  $W_u$  and  $N_u$ .

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Definition

# Graphon mean-field BSDEs with jumps

$$\begin{aligned} X_{u}(t) = & \xi_{u} + \int_{t}^{T} \int_{I} \int_{\mathbb{R}} G(u, y) f(s, x, X_{u}(s^{-}), Z_{u}(s), \ell_{u,s}(\cdot)) \mu_{y,s}(dx) dy ds \\ & - \int_{t}^{T} Z_{u}(s) dW_{u}(s) - \int_{t}^{T} \int_{E} \ell_{u,s}(e) \widetilde{N}_{u}(ds, de), \quad \text{for } t \in [0, T], \ u \in I, \end{aligned}$$

$$(4.1)$$

where  $\mu_v := \mathcal{L}(X_v)$  and  $\mu_{v,s} := \mathcal{L}(X_v(s))$ . Assume  $\forall u \in I, \xi_u \in L^2(\mathcal{F}_\tau^u)$ .

#### Definition

A solution consists of a family of processes  $\Phi := (X_u, Z_u, \ell_u)_{u \in I}$  with  $(X_u, Z_u, \ell_u)$  in  $\mathbb{S}^2(\mathbb{F}^u) \times \mathbb{H}^2(\mathbb{F}^u) \times \mathbb{H}^2_{v_u}(\mathbb{F}^u)$  for each *u* in *I*, satisfying (4.1), s.t.  $u \mapsto \mathcal{L}(X_u)$  is measurable in the weak sense,  $X_u$  is a RCLL  $\mathbb{R}$ -valued optional process, and  $Z_{\mu}$  (resp.  $\ell_{\mu}$ ) is a  $\mathbb{R}$ -valued predictable process defined on  $\Omega \times [0, T]$  (resp.  $\Omega \times [0, T] \times E$ ) s.t. the stochastic integral is well defined.

**Assumption on** *f* : For each  $u \in I$ , we assume that  $f: \Omega \times [0, T] \times \mathbb{R}^3 \times L^2_{v_u} \to \mathbb{R}; (\omega, t, x', x, z, \ell(\cdot)) \mapsto f(\omega, t, x', x, z, \ell(\cdot))$ is  $P \otimes \mathcal{B}(\mathbb{R}^3) \otimes \mathcal{B}(L^2_{v_u})$  measurable, satisfies  $f(\cdot, \cdot, 0, 0, 0, 0) \in \mathbb{H}^2(\mathbb{F}^u)$ , and *f* is Lipschitz-continuous in  $(x', x, z, \ell)$ , i.e.,  $\exists$  a constant  $C \ge 0$  s.t.  $dt \otimes d\mathbb{P}$ -a.s., for each  $(x'_1, x_1, z_1, \ell_1)$  and  $(x'_2, x_2, z_2, \ell_2)$ , we have

$$\left| f(\omega, t, x'_1, x_1, z_1, \ell_1(\cdot)) - f(\omega, t, x'_2, x_2, z_2, \ell_2(\cdot)) \right| \\ \leq C(|x'_1 - x'_2| + |x_1 - x_2| + |z_1 - z_2| + \|\ell_1 - \ell_2\|_{v_u}).$$

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# Graphon Mean-field BSDEs

Agenda

- existence, uniqueness and weak measurability of the solution
- comparison theorems under a monotonicity condition
- continuity of the solution with respect to the label index and stability of the system
- convergence of an interacting mean-field particle system with heterogeneous interactions to the graphon MFBSDE
- associated graphon dynamic risk measure and its properties

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• dual representation in the convex case.

#### Canonical coupling

$$\begin{aligned} X_u(t) = &\xi_u + \int_t^T \int_I \int_{\mathbb{R}} G(u, y) f(s, x, X_u(s^-), Z_u(s), \ell_{u,s}(\cdot)) \mu_{y,s}(dx) dy ds \\ &- \int_t^T Z_u(s) dW_u(s) - \int_t^T \int_E \ell_{u,s}(e) \widetilde{N}_u(ds, de), \quad \text{for } t \in [0, T], \ u \in I, \end{aligned}$$

- Note that different labels interact only through their laws μ<sub>u</sub>.
- To handle the measurability of  $\mathcal{L}(X_u)$  in u we can treat all processes  $(X_u, Z_u, \ell_u)_{u \in I}$  on one stochastic basis : To this purpose, we introduce a canonical probability space  $(\bar{\Omega}, \bar{\mathcal{F}}, \bar{\mathbb{P}})$ , on which we define a canonical Brownian motion  $\bar{W}$  and a common Poisson random measure  $\bar{N}(dt, de)$  with compensator v(de)dt that is specified below. We define the canonical filtered probability space  $(\bar{\Omega}, \bar{\mathcal{F}}, \bar{\mathbb{P}}, \bar{\mathbb{P}})$ , where  $\bar{\mathbb{F}} = \{\bar{\mathcal{F}}_t, t \ge 0\}$  is the completed natural filtration and  $\bar{\mathbb{P}}$  is the corresponding probability measure, generated by  $\bar{W}$  and  $\bar{N}(dt, de)$ .

We transform the original graphon system into a fully coupled system driven by a common  $(\overline{W}, \overline{N})$ , defined on a canonical space  $(\overline{\Omega}, \overline{\mathcal{F}}, \overline{\mathbb{F}}, \overline{\mathbb{P}})$ , which admits a solution with the same law. We use trivially the canonical Brownian motion  $\overline{W}$ , and make the following assumption for the jump part : **Assumption :**[Intensity measure]

The function *I* × [1,2] ∋ (*u*, *w*) → φ<sub>u</sub><sup>-1</sup>(ω − 1) ∈ ℝ is B(*I*) ⊗ B([1,2]) measurable, where φ<sub>u</sub> denotes the cumulative distribution function of v<sub>u</sub>. We define φ<sub>u</sub><sup>-1</sup>(1) as the essential supremum and φ<sub>u</sub><sup>-1</sup>(0) as the essential infimum.

The idea is to use a common Poisson r.m.  $\bar{N}$  to generate different r.m.  $N_u$  for all  $u \in I$  through the mapping  $\varphi_u^{-1}, u \in I$ . Thanks to the same time intensity of all  $N_u$ , the jumps for different labels can be coupled through  $\bar{N}$ , meaning all labels  $u \in I$  jump at the same time but with different jump sizes. Here,  $\bar{N}$  is chosen to have compensator measure v(de)dt with v being uniform on [1,2]. (We choose the interval [1,2] to avoid 0 since v should not have mass at 0). Now  $\bar{N}(dt, \varphi_u^{-1}(e-1)de)$  is a Poisson r.m. with intensity  $v_u(de)dt$ , which has the same law as  $N_u$ .

### Example

Let  $v_u$  be uniform on [1, 2+u]. Then  $\phi_u^{-1}(\omega) = 1 + (1+u)(\omega-1)$ , and the Assumption is satisfied.

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Assumption :[Coupling of terminal condition].

We also assume that  $\xi := \{\xi_u\}_{u \in I}$  can be measurably coupled,i.e.  $\forall u \in I$ ,  $\exists \overline{\xi}_u \in L^2(\overline{\mathcal{F}}_T)$  s.t.  $u \mapsto \overline{\xi}_u$  is measurable and  $\mathcal{L}(\xi_u) = \mathcal{L}(\overline{\xi}_u)$ . We denote by  $\xi \in \overline{\mathcal{M}L^2}(\mathcal{F}_T)$  if the terminal condition satisfies this assumption.

#### Example

Let  $\xi_u := aW_T^u + \sum_{i=1}^{N_u(T)} Y_i^u$ , where  $Y_i^u$  is the *i*-th jump of label *u* according to the distribution  $v_u$ . Following the canonical coupling, we have  $\bar{\xi}_u = a\bar{W}_T + \sum_{i=1}^{\bar{N}(T)} \varphi_u^{-1}(Y_i - 1)$ , where  $Y_i, i = 1, \dots, \bar{N}(T)$  are i.i.d. uniform random variables on [1,2]. If Assumption on intensity is satisfied, then  $\bar{\xi} \in \mathcal{M}L^2(\bar{\mathcal{F}}_T)$ .

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The canonically coupled graphon system is now written as follows :

$$\begin{split} \bar{X}_{u}(t) &= \bar{\xi}_{u} + \int_{t}^{T} \int_{I} \int_{\mathbb{R}} G(u, y) f(s, x, \bar{X}_{u}(s^{-}), \bar{Z}_{u}(s), \bar{\ell}_{u,s}(\cdot)) \mu_{y,s}(dx) dy ds \\ &- \int_{t}^{T} \bar{Z}_{u}(s) d\bar{W}(s) - \int_{t}^{T} \int_{E} \bar{\ell}_{u,s}(\varphi_{u}^{-1}(e-1)) \widetilde{\tilde{N}}(ds, de), \ u \in I, t \in [0, T]. \end{split}$$

$$(4.2)$$

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Note that  $\mathcal{L}(\bar{X}, \bar{Z}, \bar{\ell}) = \mathcal{L}(X, Z, \ell)$ .

#### Theorem

The coupled system (4.2) admits a unique solution  $\overline{\Phi} := (\overline{X}, \overline{Z}, \overline{\ell}) \in \mathcal{M}$  such that  $\overline{X} \in \mathcal{MS}^2(\overline{\mathbb{F}})$ . Furthermore, the graphon mean-field BSDE system (4.1) also admits a unique solution  $\Phi := (X, Z, \ell) \in \mathcal{M}$ , and  $I \ni u \mapsto \mathcal{L}(X_u)$  is measurable.

We denote by  $\mathcal{M}$  the space

$$\mathcal{M} := \{ \Phi := \{ (X_u, Z_u, \ell_u(\cdot)) \in \mathbb{S}^2(\mathbb{F}^u) \times \mathbb{H}^2(\mathbb{F}^u) \times \mathbb{H}^2_{v_u}(\mathbb{F}^u) \}_{u \in I}, \text{ such that}$$
$$\|\Phi\|_{\mathcal{M}} := \sup_{u \in I} \left( \mathbb{E}[\sup_{t \in [0, T]} |X_u(t)|^2] + \mathbb{E}[\int_0^T |Z_u(t)|^2 dt + \mathbb{E}[\int_0^T \|\ell_{u,t}\|_{v_u}^2 dt] \right)^{1/2} < \infty \}$$

For the measurability, we prove that  $u \mapsto \overline{X}_u$  is measurable in u, and thus also the map  $u \mapsto \mathcal{L}(\overline{X}_u)$ .

Then since the canonical coupling does not change the law of the first component of solution of the original system (4.1), we have  $\mathcal{L}(X_u) = \mathcal{L}(\bar{X}_u)$  for all  $u \in I$ . Thus  $u \mapsto \mathcal{L}(X_u)$  is measurable.

#### Assumption A.1 (Monotonicity assumption)

 $\forall u \in I, (x', x, z, \ell_1, \ell_2) \in \mathbb{R}^3 \times (L^2_{v_u})^2, \exists \phi_{u,t}^{x', x, z, \ell_1, \ell_2} \in L^2_{v_u}, \text{ measurable, bounded s.t.}$ 

$$f(t,x',x,z,\ell_1)-f(t,x',x,z,\ell_2)\geq \langle \phi_{u,t}^{x',x,z,\ell_1,\ell_2},\ell_1-\ell_2\rangle_{v_u},$$

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 $\text{ with } \varphi_{u,t}^{x',x,z,\ell_1,\ell_2}(y) \geq -1 \quad \text{and} \quad |\varphi_{u,t}^{x',x,z,\ell_1,\ell_2}(y)| \leq \psi(y), \text{ for some } \psi \in L^2_{v_u}.$ 

### Theorem (Comparison theorem)

Let  $\xi^1, \xi^2 \in \overline{\mathcal{ML}^2}(\mathcal{F}_T)$  and denote  $(X^i, Z^i, \ell^i)$  the solution of graphon mean-field BSDE (4.1) associated to  $(\xi^i, f^i)$ , i = 1, 2. Assume

- f<sub>1</sub> satisfies Assumption A.1, and f<sub>2</sub> is non-decreasing in x';
- For each  $u \in I \setminus H$  with H a zero Lebesgue measure subset of I,  $\xi_u^2 \ge \xi_u^1$  a.s. and  $f_2(\omega, t, x', x, z, \ell) \ge f_1(\omega, t, x', x, z, \ell)$  a.s. for all  $(t, x', x, z, \ell) \in \mathbb{R}^4 \times L^2_{v_u}$ .

Then for all  $t \in [0, T]$  and  $u \in I \setminus H$ , we have  $X_u^2(t) \ge X_u^1(t)$  a.s..

Strict comparison thm (under Assumption A.1 with strict inequality).

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Continuity of the solution with respect to the label index u

For each  $u \in I$ , assume

- (i)  $u \to \mathcal{L}(\xi_u)$  is continuous w.r.t. the  $\mathcal{W}_2$  metric.
- (ii) there exists a finite collection of intervals  $\{I_i : i = 1, ..., N\}$  such that  $I = \bigcup_i I_i$ , and for each  $i \in \{1, ..., N\}$ , we have G(u, v) is continuous at u for each  $v \in I \setminus H_i$  for some zero Lebesgue measure set  $H_i$ .

Then for each  $i \in \{1, ..., N\}$ , the map  $I_i \ni u \to \mathcal{L}(X_u)$  is continuous w.r.t. the  $\mathcal{W}_{2,T}$  metric.

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#### Stability

Convergence issues when the underlying graphon *G* is induced by a sequence of graphons  $G_n$  converging to *G*, in the sense of cut norm  $||G_n - G||_{\Box} \rightarrow 0$ .

(Recall that  $||G||_{\Box} := \sup_{A,B \in \mathcal{B}(I)} \left| \int_{A \times B} G(u,v) du dv \right|$ .)

Technical assumption : Assume that for each *u* ∈ *I*, the driver *f* can be characterized as E<sup>e</sup><sub>u</sub>[*f*(·, ℓ(*e*))], where E<sup>e</sup><sub>u</sub> means taking integration of *f*(·, ℓ(*e*)) with respect to *e* under the measure v<sub>u</sub>, and *f* is Lipschitz continuous in all parameters except time *t*.

Then the corresponding solution of the  $G_n$  graphon mean-field BSDE converges (in some sense) to the solution of the *G* graphon mean-field BSDE and the law of the *X* component also converges in an integral sense of the Wasserstein distance  $\mathcal{W}_{2,T}$  on *I*:

$$\int_{I} \mathcal{W}_{2,T}(\mathcal{L}(X_u),\mathcal{L}(X_u^n))\to 0.$$

#### Theorem

Let  $(X, Z, \ell)$  and  $(X^n, Z^n, \ell^n)$  be the solutions of (4.1) associated with graphons G and  $G_n$ , terminal condition  $\xi$  and  $\xi^n$ , respectively. Then

$$\mathbb{E} \Big[ \int_{I} (\sup_{t \in [0,T]} |X_{u}^{n}(t) - X_{u}(t)|^{2} + \int_{0}^{T} |Z_{u}^{n}(t) - Z_{u}(t)|^{2} dt + \int_{0}^{T} \|\ell_{u,t}^{n} - \ell_{u,t}\|_{v_{u}}^{2} dt \Big) du \Big] \\ \leq C \Big[ \int_{I} \mathbb{E} |\xi_{u} - \xi_{u}^{n}|^{2} du + C_{M} \|G - G_{n}\|_{\Box} + \varepsilon(M) \Big],$$

where *M* is some large constant, *C<sub>M</sub>* is some constant depends on *M* and  $\varepsilon(M)$  is some constant converging to 0 as *M* goes to  $\infty$ . If  $||G_n - G||_{\Box} \to 0$  and  $\mathbb{E}[\int_I |\xi_u - \xi_u^n|^2 du] \to 0$  as  $n \to \infty$ , it follows that  $\mathbb{E}[\int_I (\sup_{t \in [0,T]} |X_u^n(t) - X_u(t)|^2 + \int_0^T |Z_u^n(t) - Z_u(t)|^2 dt + \int_0^T ||\ell_{u,t}^n - \ell_{u,t}||^2_{v_u} dt) du] \to 0$ , and consequently  $\int_I \mathcal{W}_{2,T}(\mathcal{L}(X_u), \mathcal{L}(X_u^n)) \to 0$ .

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Proof : use a truncation and approximation argument

## Example (Converging graphons)

For a size *n* adjacency matrix *A*, we define the associated step graphon  $G_A$  as :

 $G_A(u,v) := A_{ij}, \quad \text{for} \quad (u,v) \in I_i^n \times I_j^n,$ 

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where  $I_i^n := ((i-1)/n, i/n]$ , for i = 2, ..., n and  $I_1^n := [0, 1/n]$ . Let  $\zeta^n$  be the adjacency matrix of an Erdös-Rényi random graph  $\mathcal{G}(n, p_n)$ . If  $p_n = p$  is fixed as  $n \to \infty$ , then it is well known that, as  $n \to \infty$ , the associated graphon  $\mathcal{G}_{\zeta^n}$  converges in cut norm to the constant graphon  $\mathcal{G} \equiv p$ . The following theorem gives another stability result which provides the convergence of graphon mean-field BSDEs in the space  $\mathcal{M}$ .

#### Theorem

$$\sup_{u\in I} \mathbb{E} \Big[ \sup_{t\in[0,T]} |X_{u}^{n}(t) - X_{u}(t)|^{2} + \int_{0}^{T} |Z_{u}^{n}(t) - Z_{u}(t)|^{2} dt + \int_{0}^{T} ||\ell_{u,t}^{n} - \ell_{u,t}||_{v_{u}}^{2} dt \Big]$$
  
$$\leq C \Big[ \sup_{u\in I} \mathbb{E} |\xi_{u} - \xi_{u}^{n}|^{2} + C(M) ||G - G_{n}||_{\infty \to \infty} + \varepsilon(M) \Big] \to 0.$$

Consequently, if  $||G_n - G||_{\infty \to \infty} \to 0$  and  $\sup_{u \in I} \mathbb{E}[|\xi_u - \xi_u^n|^2] \to 0$  as  $n \to \infty$ , then

$$\mathcal{W}_{2,T}^{\mathcal{M}}(\mathcal{L}(X),\mathcal{L}(X^n)) \to 0.$$

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Convergence of interacting particle systems to Graphon MF-BSDEs

Consider a sequence of *N* particle graphon interacting systems.

$$X_{i}^{N}(t) = \xi_{i}^{N} + \int_{t}^{T} \frac{1}{N} \sum_{j=1}^{N} \zeta_{ij}^{N} f(s, X_{j}^{N}(s^{-}), X_{i}^{N}(s^{-}), Z_{i}^{N}(s), \ell_{s}^{N,i}(\cdot)) ds$$

$$- \int_{t}^{T} Z_{i}^{N}(s) d\widehat{W}_{i}(s) - \int_{t}^{T} \int_{E} \ell_{s}^{N,i}(e) \widetilde{\widehat{N}}_{i}(ds, de), \quad t \in [0, T]$$

$$(4.3)$$

where for the *i*-th particle  $\widehat{W}_i := W_{\frac{i}{N}}$  and  $\widehat{N}_i(dt, de) = N_{\frac{i}{N}}(dt, de)$  are chosen to be the same ones associated to label i/N.

Assume  $\xi_i^N \in L^2(\mathcal{F}_T^{i/N})$  for all  $i = 1, \dots, N$ .

Here,  $(\zeta_{ij}^N : i, j \in [N] \times [N])$  is a  $N \times N$  symmetric matrix, describing the strength of interaction between particle *i* and *j*.

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Define the space 
$$\mathcal{M}^N := \{ (X_i, Z_i, \ell_i(\cdot)) \in \mathbb{S}^2(\mathbb{F}^{i/N}) \times \mathbb{H}^2(\mathbb{F}^{i/N}) \times \mathbb{H}^2_{v_i^N}(\mathbb{F}^{i/N}) \}_{i=1}^N, \text{ s.t. }$$
  
 $\|\Phi^N\|_{\mathcal{M}^N} := \max_{i=1,\dots,N} (\mathbb{E}[\sup_{t \in [0,T]} |X_i(t)|^2] + \mathbb{E}[\int_0^T |Z_i(t)|^2 dt + \mathbb{E}[\int_0^T \|\ell_{i,t}\|_{v_i}^2 dt])^{1/2} < \infty \},$   
where  $v_i^N := v_{i/N}.$ 

#### Theorem

The N-coupled BSDE system (4.3) admits a unique solution  $\Phi^N \in \mathcal{M}^N$ .

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Assumption : For a given graphon *G*, we say that  $\zeta^N := {\zeta_{ij}^N}_{i,j \in [N]}$  satisfies the regularity assumption with graphon *G* if either :

(i) 
$$\zeta_{ij}^N = G(\frac{i}{N}, \frac{j}{N});$$

(ii)  $\zeta_{ij}^N = \text{Bernoulli}(G(\frac{i}{N}, \frac{j}{N}))$  independently for all  $1 \le i \le j \le N$  and independent of  $\{W_u, N_u, \xi_u : u \in I\}$ .

#### Convergence of finite particle systems to the graphon BSDE

#### Theorem

Suppose that  $\zeta^N$  satisfies the regularity assumption with graphon G, G is Lipschitz continuous and  $\max_{i=1,...,N} \mathbb{E} |\xi_i^N - \xi_{\frac{i}{N}}|^2 = O(N^{-1})$ . Then the unique solution  $\Phi^N$  of (4.3) converges to the unique solution of (4.1) with the convergence rate  $1/\sqrt{N}$  and

$$\max_{i=1,...,N} \mathbb{E} \left[ \sup_{t \in [0,T]} |X_{i}^{N}(t) - X_{\frac{i}{N}}(t)|^{2} + \int_{0}^{T} |Z_{i}^{N}(t) - Z_{\frac{i}{N}}(t)|^{2} dt + \int_{0}^{T} \|\ell_{t}^{i,N} - \ell_{t}^{\frac{i}{N}}\|_{v}^{2} dt \right]$$
  
$$\leq CN^{-1} + C \max_{i=1,...,N} \mathbb{E} |\xi_{i}^{N} - \xi_{\frac{i}{N}}|^{2} = O(N^{-1}),$$

for all  $N \in \mathbb{N}$  and some constant *C*. Furthermore, for  $\kappa_t^N = \frac{1}{N} \sum_{i=1}^N \delta_{X_i^N(t)}$  and  $\kappa_t = \int_I \mathcal{L}(X_u(t)) du$ , we have

$$\sup_{\mathbf{t}\in[0,T]} \mathbb{E}\left[\left(\mathcal{W}_{2}(\mathbf{\kappa}_{t}^{N},\mathbf{\kappa}_{t})\right)^{2}\right] \leq CN^{-1/2}.$$
(4.4)

(INRIA, Mathrisk)

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Similar convergence result is obtained when the heterogeneous interaction weights are sampled from a sequence of convergent graphons (instead of from the limiting graphon)

# Graphon dynamic risk measure

For  $\xi \in \mathcal{M}L^2(\mathcal{F}_T)$  (i.e.  $\xi_u \in \mathcal{F}_T^u \ \forall u \in I$ , and  $\xi^u, u \in I$  can be canonically coupled to satisfy the label measurability) representing a financial position at *T*, we interpret  $\rho_{u,t}(\xi, T) := -X_u(t, \xi, T)$ , for each  $u \in I$ , where  $\{X_u(t, \xi, T)\}_{u \in I}$  is the solution of the graphon mean-field BSDE system, as the risk measure of  $\xi$  at time *t* and position  $u \in I$ . Then  $\rho_t(\xi, T) := \{\rho_{u,t}(\xi, T)\}_{u \in I}$ is called the graphon associated dynamic risk measure.

**Interpretation :** a regulator imposes the capital to be  $\xi$  at time T, and the risk measure  $\rho_t(\xi, T)$  is interpreted as the acceptable levels of liquidity at time *t*, for a given driver capturing how a representative bank's position evolves with dependence on the heterogeneous mean-field interactions in the system.

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# Properties of global dynamic risk measures

- Consistency. Let τ < T be a stopping time. Then ∀t ≤ τ, ρ<sub>t</sub>(ξ, T) = ρ<sub>t</sub>(−ρ<sub>τ</sub>(ξ, T), τ) a.s. (consequence of the uniqueness result).
- Continuity. Let  $\{\tau^{\alpha}, \alpha \in \mathbb{R}\}$  be a family of stopping times converging a.s. to  $\tau^{\alpha_0}$  as  $\alpha \to \alpha_0$ . Let  $\{\xi^{\alpha}, \alpha \in \mathbb{R}\}$  be a sequence of random families s.t. for each  $\alpha \in \mathbb{R}, \xi^{\alpha,u}$  is  $\mathcal{F}^{\,\,u}_{\tau^{\alpha}}$ -measurable,  $u \in I$  and  $\mathbb{E}[\operatorname{ess\,sup}_{\alpha,u}(\xi^{\alpha,u})^2] < \infty$ . Suppose also that  $\xi^{\alpha,u}$  converges a.s. to a  $\mathcal{F}^{\,\,u}_{\tau^{\alpha_0}}$ -measurable r.v.  $\xi^{\,\,u}$  as  $\alpha \to \alpha_0$ . Then for each stopping time  $\widehat{\tau} < \tau^{\alpha}, \alpha \in \mathbb{R}$ , the r.v.  $\rho_{\widehat{\tau}}(\xi^{\alpha}, \tau^{\alpha}) \to \rho_{\widehat{\tau}}(\xi, \tau^{\alpha_0})$  a.s. and the processes  $\rho_u(\xi^{\alpha}, \tau^{\alpha}) \to \rho_u(\xi, \tau^{\alpha_0})$  for all  $u \in I$ , as  $\alpha \to \alpha_0$ .
- *Monotonicity*.  $\rho$  is nonincreasing with respect to  $\xi$ . i.e., for each T > 0 and each  $\xi^1, \xi^2 \in \mathcal{M}L^2(\mathcal{F}_T)$ , if  $\xi^1 \ge \xi^2$  a.s., then a.s.  $\rho_t(\xi^1, T) \le \rho_t(\xi^2, T), 0 \le t \le T$ . (consequence of comparison theorem)

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- *Homogeneity* : If *f* is positively homogeneous wrt  $(x', x, z, \ell)$ , i.e., for a > 0,  $f(t, ax', ax, az, al) = af(t, x', x, z, \ell)$ , then the risk measure  $\rho$  is positively homogeneous wrt  $\xi$ , that is, for all  $\lambda \ge 0$ ,  $t \in [0, T]$  and  $\xi \in \mathcal{M}L^2(\mathcal{F}_T)$ , we have  $\rho_t(\lambda \xi, T) = \lambda \rho_t(\xi, T)$ .
- Translation invariance : If f depends only on (t, x' − x, z, ℓ), then the risk measure satisfies the translation invariance property : for any ξ ∈ ML<sup>2</sup>(F<sub>T</sub>), t<sub>0</sub> ∈ [0, T] and ξ' ∈ ML<sup>2</sup>(F<sub>t0</sub>),

$$ho_t(\xi+\xi',T)=
ho_t(\xi,T)-\xi' ext{ for all } t\in[t_0,T].$$

- No Arbitrage. when strict comparison holds, then for each T > 0and each  $\xi^1, \xi^2 \in \mathcal{ML}^2(\mathcal{F}_T)$ , if  $\xi^1 \ge \xi^2$  and  $\rho_t(\xi^1, T) = \rho_t(\xi^2, T)$ a.s. on an event  $A \in \mathcal{F}_t$ , then  $\xi^1 = \xi^2$  a.s. on A.
- Convexity If f is concave with respect to (x, z, l), then the dynamic risk measure is convex, that is for any λ ∈ [0, 1] and ξ<sup>1</sup>, ξ<sup>2</sup> ∈ ML<sup>2</sup>(F<sub>T</sub>), we have

$$\rho_t(\lambda\xi^1+(1-\lambda)\xi^2,T)\leq\lambda\rho_t(\xi^1,T)+(1-\lambda)\rho_t(\xi^2,T).$$

Special case. No Graphons and f independent on x and concave Quenez-A.S. SPA 2013

$$-dX_t = f(t, \omega, Z_t, l_t(\cdot))dt - Z_t dW_t - \int_{\mathbb{R}^*} l_t(e) \tilde{N}(dt, de); \quad X_T = \xi,$$

Consider the polar function of  $f(t, \omega, z, \ell)$ :

$$f^*(\omega, t, \alpha^1, \alpha^2) := \sup_{(z,\ell) \in \mathbb{R} \times L^2_{\nu}} [f(\omega, t, z, \ell) - \alpha^1 z - \langle \alpha^2, \ell \rangle_{\nu}].$$

Let  $\mathcal{A}_{\mathcal{T}}$  the set of predictable proc.  $\alpha_s = (\alpha_s^1, \alpha_s^2)$  s.t.  $f^*(t, \alpha^1, \alpha^2) \in H^2$  (it implies in particular  $\alpha_s^2(u) \ge -1$ ). For  $\alpha \in \mathcal{A}_{\mathcal{T}}$ , let  $Q^{\alpha}$  be the probability (absolutely cont. wrt to *P*) which admits  $\Gamma_{\mathcal{T}}^{\alpha}$  as density wrt *P* on  $\mathcal{F}_{\mathcal{T}}$ , where

$$d\Gamma_t^{\alpha} = \Gamma_{t-}^{\alpha} (\alpha_t^1 dW_t + \int_{\mathbb{R}^*} \alpha_t^2(e) d\tilde{N}(dt, de)); \quad \Gamma_0^{\alpha} = 1.$$

Then

$$-X_0 = \sup_{\alpha \in \mathcal{A}_{\mathcal{T}}} \left[ \mathbb{E}^{\mathcal{Q}^{\alpha}}(-\xi) - \zeta(\alpha, \mathcal{T}) \right]$$

where the function  $\zeta$ , called *penalty function*, is defined, by

$$\zeta(\alpha, T) := \mathbb{E}^{Q^{\alpha}} [\int_{0}^{T} f^{*}(s, \alpha_{s}) ds]$$

Example : the entropic risk measure :

$$\rho_t(\xi, T) := \frac{1}{\gamma} \ln \mathbb{E}[\exp(-\gamma \xi) \mid \mathcal{F}_t]$$

is associated to the BSDE with driver  $g(z) := \frac{1}{2}\gamma z^2$ In this case the penalty function is

$$\zeta(Q) = \mathbb{E}[\frac{dQ}{dP}\ln\frac{dQ}{dP}]$$

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# **Dual representation**

$$\begin{aligned} X_u(t) = &\xi_u + \int_t^T \int_I \int_{\mathbb{R}} G(u, y) f(s, x, X_u(s^-), Z_u(s), \ell_{u,s}(\cdot)) \mu_{y,s}(dx) dy ds \\ &- \int_t^T Z_u(s) dW_u(s) - \int_t^T \int_E \ell_{u,s}(e) \widetilde{N}_u(ds, de), \quad \text{for } t \in [0, T], \ u \in I, \end{aligned}$$

Suppose that *f* is concave with respect to  $(x', x, z, \ell)$  and non-decreasing in x'. Let  $F_u$  denote the drift driver of the *u* component :

$$F_u(\omega,t,\mathcal{L}(X_t),x,z,\ell(\cdot)) := \int_I \int_{\mathbb{R}} G(u,y) f(t,x',x,z,\ell(\cdot)) \mu_{y,t}(dx') dy.$$

For each  $(\omega, t)$  and  $u \in I$ , let  $(F_u)^*$  the Fenchel-Legendre transform defined as

$$(F_{u})^{*}(\omega, t, \mathcal{L}(Y), \beta_{u}, \alpha_{u}^{1}, \alpha_{u}^{2}) := \sup_{(X, x, z, \ell) \in L^{2, l}(\bar{\mathcal{F}}_{l}) \otimes \mathbb{R}^{2} \otimes L^{2}_{v_{u}}} \{F_{u}(\omega, t, \mathcal{L}(X), x, z, \ell) \\ - \langle X, Y \rangle_{L^{2, l}} - \beta_{u} x - \alpha_{u}^{1} z - \langle \alpha_{u}^{2}, \ell_{u} \rangle_{v_{u}} \}.$$

For  $u \in I$  and given predictable process  $\alpha_u = (\alpha_u^1, \alpha_u^2)$ , let  $Q_u^{\alpha}$  be the proba abs. continuous wrt  $\mathbb{P}$ , which admits  $\Gamma^{\alpha_{u,T}}$  as density, where  $\Gamma^{\alpha_u}$  is solution of

$$d\Gamma^{\alpha_{u,t}} = \Gamma^{\alpha_{u,t-}} \big( \alpha_{u,t}^{1} dW_{u}(t) + \int_{E} \alpha_{u,t}^{2}(e) d\widetilde{N}_{u}(dt, de) \big), \quad \Gamma^{\alpha_{u,0}} = 1$$

Let  $\mathcal{A}_{\mathcal{T}}^{I}$ : set of families of processes  $(\gamma_{t}, \beta_{t}, \alpha_{t})_{t \in [0, T]}$ , where  $(\gamma_{t})_{t \in [0, T]}$  (with  $\gamma_{t} := (\gamma_{t}^{\mu, \nu})_{u, \nu \in I}$ ) progressively measurable,  $(\beta_{t}, \alpha_{t})_{t \in [0, T]}$  predictable, and s.t.

•  $\alpha := \{\alpha_u\}_{u \in I}$  s.t.  $\forall u \in I, \ \int_0^T (\alpha_{u,s}^1)^2 ds + \int_0^T \|\alpha_{u,s}^2\|_{\nu_u}^2 ds$  is bounded, and  $\alpha_{u,t}^2(y) > -1 \nu_u(dy)$ -a.s. for all  $t \in [0, T]$ . (This implies  $\Gamma^{\alpha_{u,t}} > 0$  a.s. on [0, T] and  $(\Gamma^{\alpha_{u,t}})_{t \in [0, T]} \in \mathbb{S}^2$ ).

• 
$$\forall (u,v) \in I, (\Gamma^{\alpha}_{v,t}e^{\int_0^t \gamma^{\mu,v}_y dy})_{t \in [0,T]} \in \mathbb{H}^2;$$

• 
$$\forall v \in I, \{(F_v)^*(t, (\frac{\Gamma_t^{\alpha_{v_1}}H_{0,t}^{\beta_{v_1},\gamma^{v,v_1}}\gamma_t^{v,v_1}}{\mathbb{E}[\Gamma_t^{\alpha_{v_1}}\int_I H_{0,t}^{\beta_{v,\gamma},\gamma^{v_1,v}}d_{v_1}]})_{v_1 \in I}, \beta_{v,t}, \alpha_{v,t}^1, \alpha_{v,t}^2(\cdot))\}_{t \in [0,T]} \in \mathbb{H}^2.$$

Theorem (Dual representation) For each  $t \in [0, T]$ , we have :

$$\mathbb{E}[\int_{I} \rho_{\nu,t}(\xi,T) d\nu] = \sup_{(\gamma,\beta,\alpha)\in\mathcal{A}_{T}^{I}} \{\int_{I} \mathbb{E}^{Q_{\nu}^{\alpha}} [-(\int_{I} H_{t,T}^{\beta_{\nu},\gamma^{\mu,\nu}} du)\xi_{\nu}] d\nu - \int_{I} \zeta_{\nu,t}(\gamma,\beta,\alpha,T) d\nu\},\$$

where  $\zeta_{v,t}(\gamma,\beta,\alpha,T) :=$ 

$$\begin{split} \int_{t}^{T} \mathbb{E}^{\mathcal{Q}_{v}^{\alpha}} \big[ \big( \int_{I} \mathcal{H}_{t,s}^{\beta_{v},\gamma^{\mu,\nu}} du \big) (\mathcal{F}_{v})^{*} \big( s, \big( \frac{\Gamma_{s}^{\alpha_{v_{1}}} \mathcal{H}_{t,s}^{\beta_{v_{1}},\gamma^{\nu,\nu_{1}}}}{\mathbb{E} [\Gamma_{s}^{\alpha_{v}} \int_{I} \mathcal{H}_{t,s}^{\beta_{v},\gamma^{\nu_{1},\nu}} dv_{1}]} \big)_{v_{1}}, \beta_{v,s}, \alpha_{v,s}^{1}, \alpha_{v,s}^{2}(\cdot) \big) \big] ds, \\ \mathcal{H}_{t,s}^{\beta,\gamma} := \exp\{ \int_{t}^{s} (\beta_{y} + \gamma_{y}) dy \}. \end{split}$$

Moreover,  $\exists (\overline{\gamma}, \overline{\beta}, \overline{\alpha}) \in \mathcal{A}_{T}^{\prime}$  attaining the supremum

(INRIA, Mathrisk)

#### Steps of the proof :

- establish bounds on the effective domain of *F*\*.
- provide some explicit form to conjugacy relations relying on a Mean-Field Graphon FSDE

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#### Happy birthday Ying!

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**Wasserstein distances.** Given a Polish space S, denote by  $\mathcal{D}([0, T], S)$  the space of RCLL functions from [0, T] to S, equipped with the Skorokhod topology. Let  $\mathcal{D}_m := \mathcal{D}([0, T], \mathbb{R}^m)$ . Denote by  $\mathcal{P}(S)$  the space of probability measures on S.

Wasserstein distances between two probability measures  $\mu$  and  $\nu$  :

$$\mathcal{W}_{2}(\mu, \mathbf{v}) := (\inf\{\mathbb{E}[|X_{1} - X_{2}|^{2}] : \mathcal{L}(X_{1}) = \mu, \mathcal{L}(X_{2}) = \mathbf{v}\})^{1/2}, \text{ for } \mu, \mathbf{v} \in \mathcal{P}(\mathbb{R}^{m}),$$
  
$$\mathcal{W}_{2,T}(\mu, \mathbf{v}) := (\inf\{\sup_{t \in [0,T]} \mathbb{E}|X_{1}(t) - X_{2}(t)|^{2} : \mathcal{L}(X_{1}) = \mu, \mathcal{L}(X_{2}) = \mathbf{v}\})^{1/2}, \text{ for } \mu,$$

For two families of probability measures  $\mu = {\{\mu_u\}}_{u \in I}$  and  $\nu = {\{\nu_u\}}_{u \in I}$ , set

$$\mathcal{W}_2^{\mathcal{M}}(\mu, \mathbf{v}) := \sup_{u \in I} \mathcal{W}_2(\mu_u, \mathbf{v}_u), \text{ for } \mu, \mathbf{v} \in \mathscr{P}(\mathscr{M}L^2) \text{ for all } t \in [0, T],$$

and

$$\mathcal{W}_{2,T}^{\mathcal{M}}(\mu, \nu) := \sup_{u \in I} W_{2,T}(\mu_u, \nu_u), \text{ for } \mu, \nu \in \mathscr{P}(\mathcal{MS}^2).$$

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For Lipschitz continuity, we need a stronger assumption.

There exists a finite collection of intervals  $\{I_i : i = 1, ..., N\}$  such that  $I = \bigcup_i I_i$ , and for some constant *C*, we have for all  $u_1, u_2 \in I_i$ ,  $v_1, v_2 \in I_j$ , and  $i, j \in \{1, ..., N\}$ ,

$$\mathcal{W}_2(\mathcal{L}(\xi_{u_1}),\mathcal{L}(\xi_{u_2})) \leq C|u_1-u_2|,$$

and,

$$|G(u_1, v_1) - G(u_2, v_2)| \le C(|u_1 - u_2| + |v_1 - v_2|).$$